

ELECTRICAL SYSTEMS OF THE ELECTRIC MOTORCYCLE

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Overview

- Project History/Background
- Motorcycle Electrical Systems Description
- This Year's Project Designs
- Proposed Implementation/Future Work

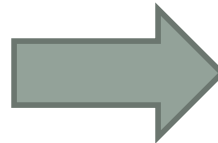
SCV Project History

- Began in 2006 as the Solar Commuter Vehicle Project
- Research project to explore feasibility of electric motorcycles
- Assembled from a Kawasaki Ninja motorcycle



Brushed DC Motor Conversion

- Gasoline engine to brushed DC motor with lead acid batteries.

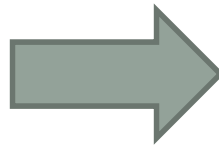


Motor Upgrade

	Brushed	Brushless
Rotor Movement Mechanism	Physical Contacts (Causing Mechanical Wear)	Induced Magnetic Fields from Control Circuitry
Efficiency	Decent	Better



Brushed Motor



Brushless Motor

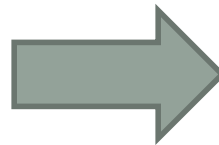
More complicated but higher quality and more efficient

Battery Upgrade

	Lead-Acid	Lithium-Ion
Construction	Lead Dioxide (PbO ₂)	Lithium Metal Ions
Performance/Maintenance	Undesirable	Desirable
Energy/Weight Ratio	Low	High
Applications	Non-weight, space critical applications (Car Starters)	Low weight, low space consumption



Lead-Acid



Lithium-Ion

Better Performance, High Energy Density

Current Power Systems Overview

Battery Pack



Stores and Delivers Charge

Motor Controller



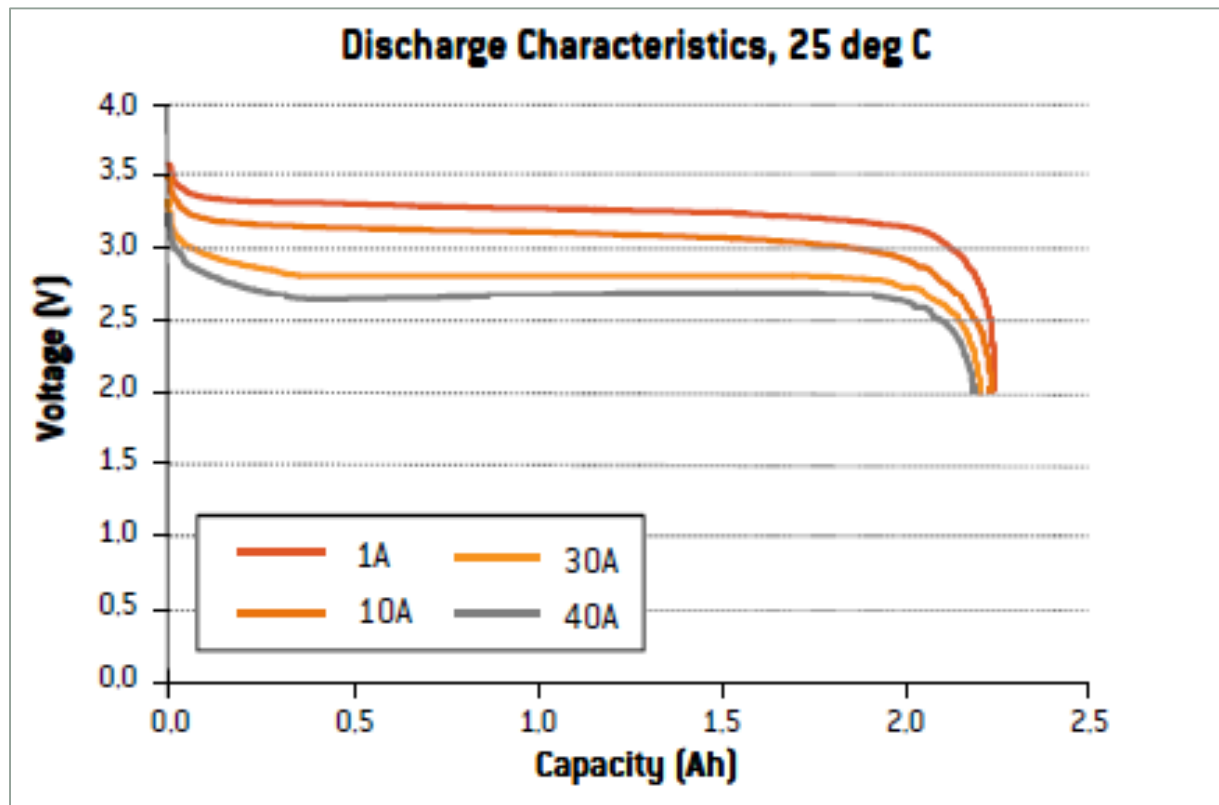
Provides regulated battery pack energy to the motor

Motor



Our Batteries

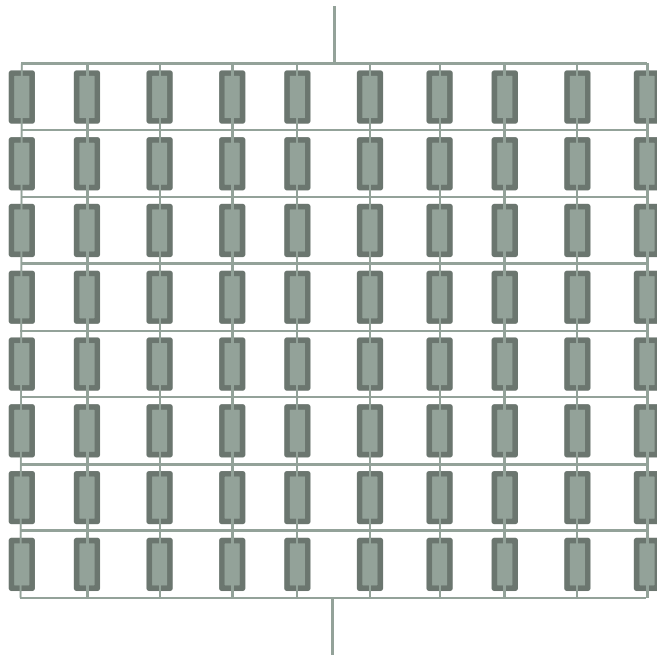
- Operating Cell Voltage Range 2.5V-3.6V



Our Battery Pack

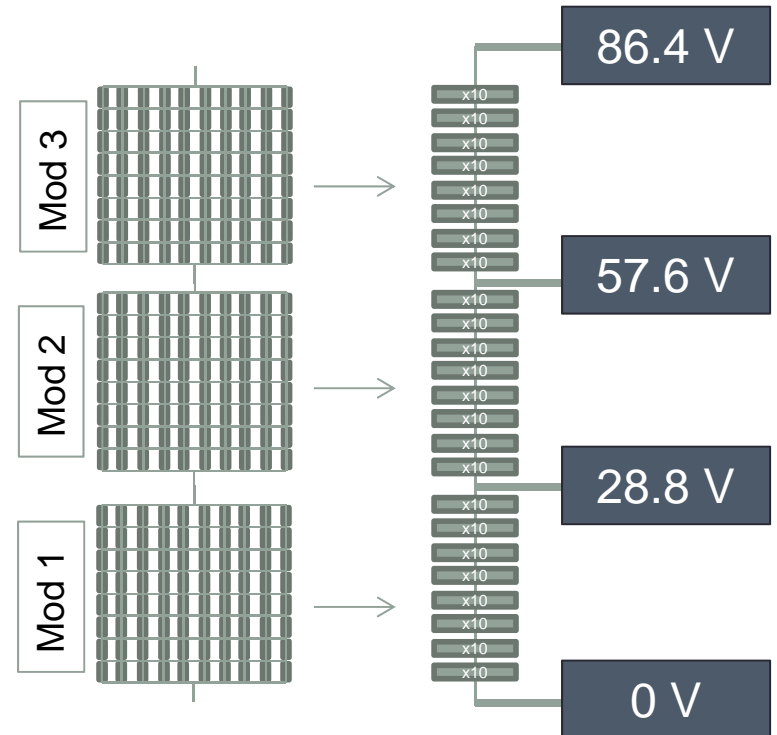


Battery Module



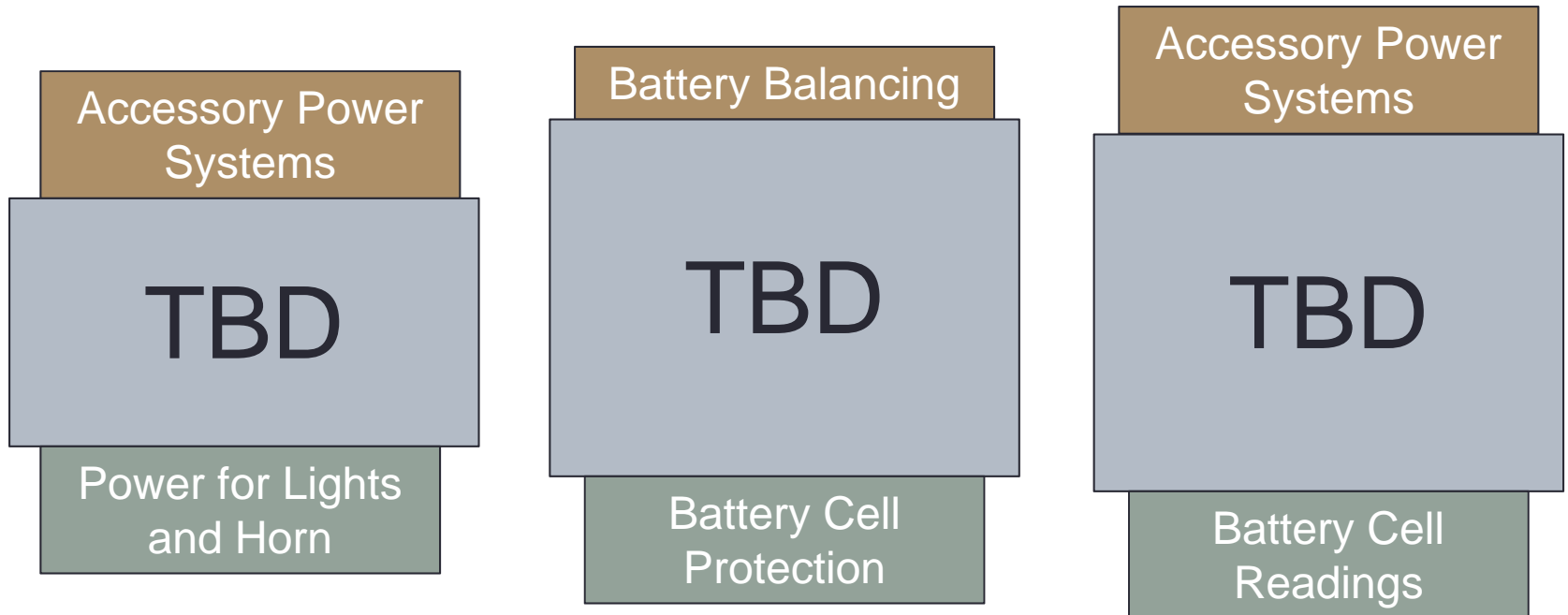
20-28.8V

Battery Pack

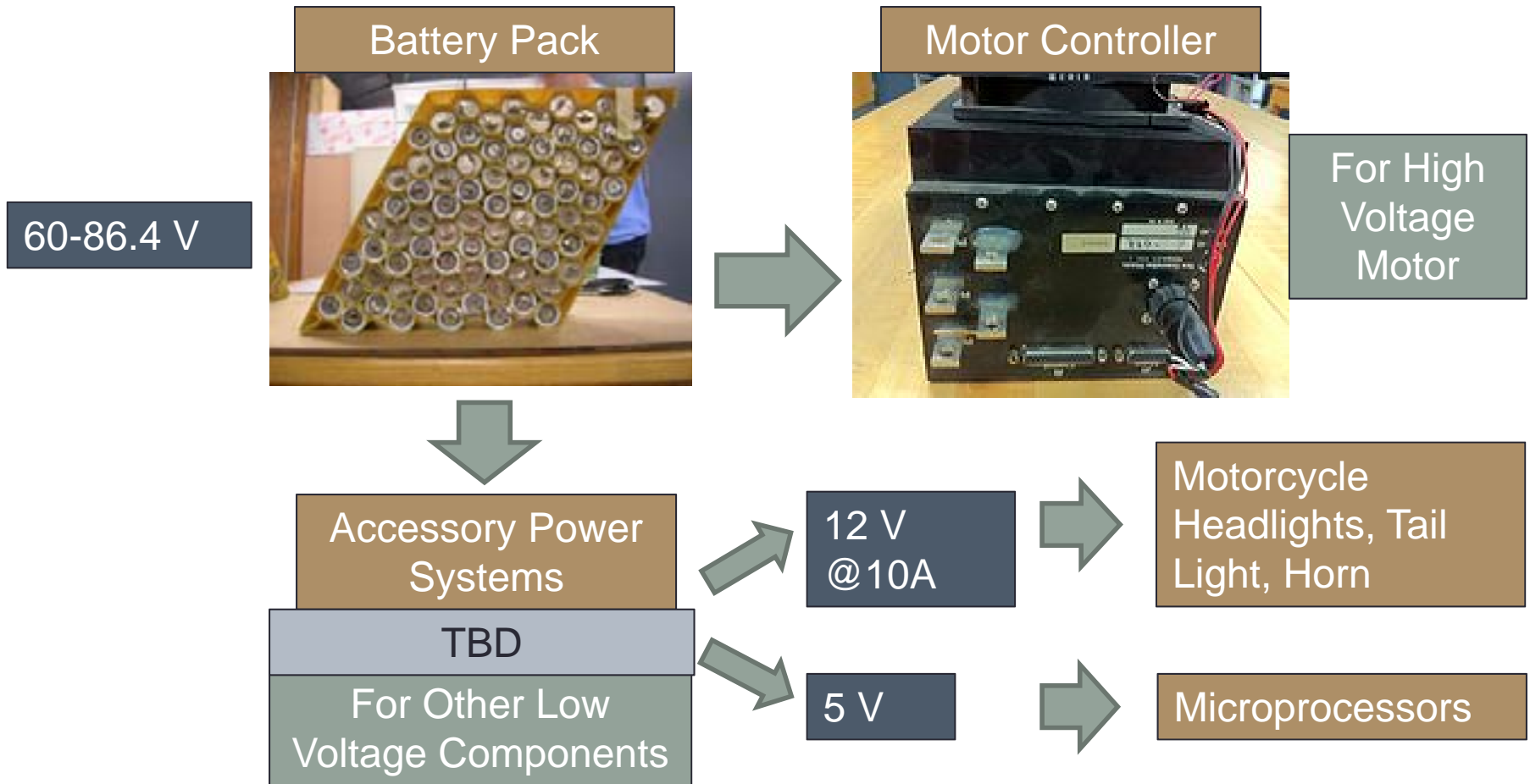


Tasks

- To-Be-Designed (TBD) Projects for this year



Accessory Power Outline



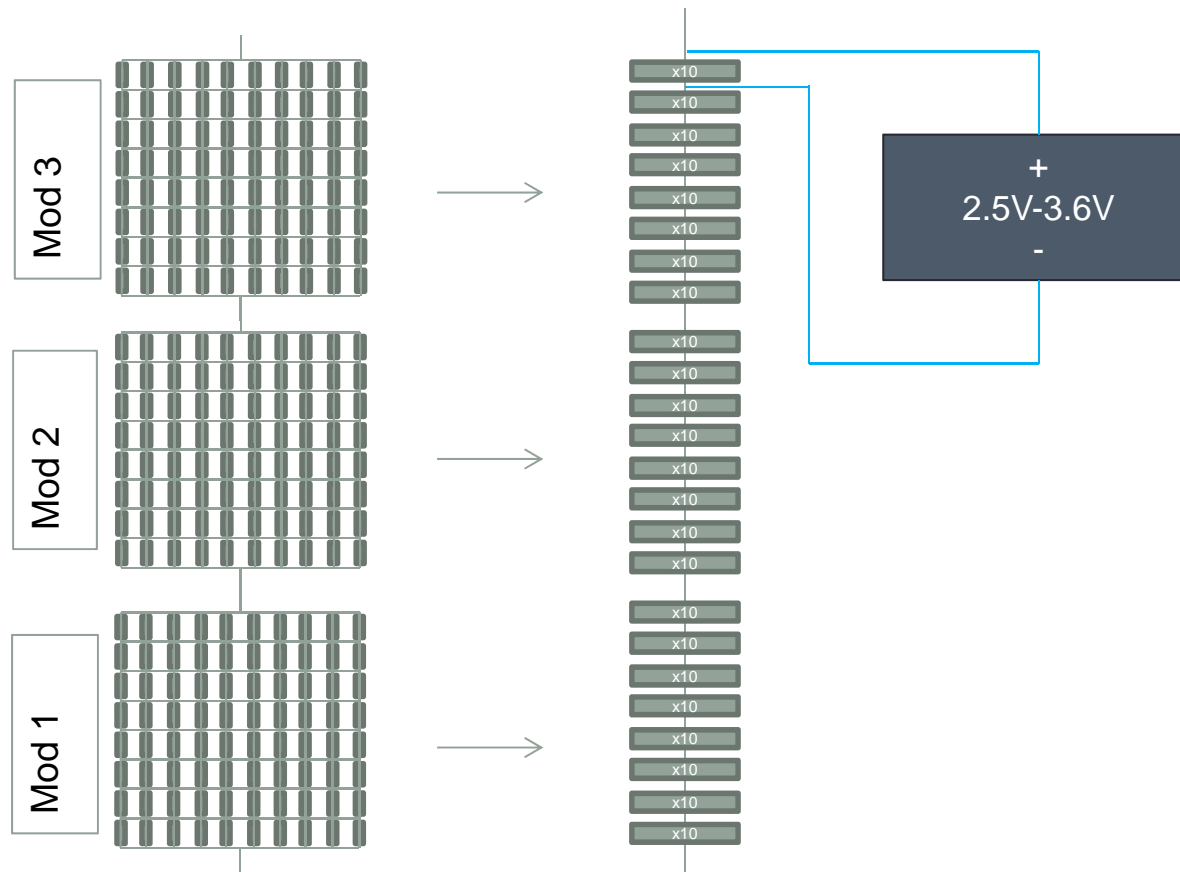
Accessory Power System Design



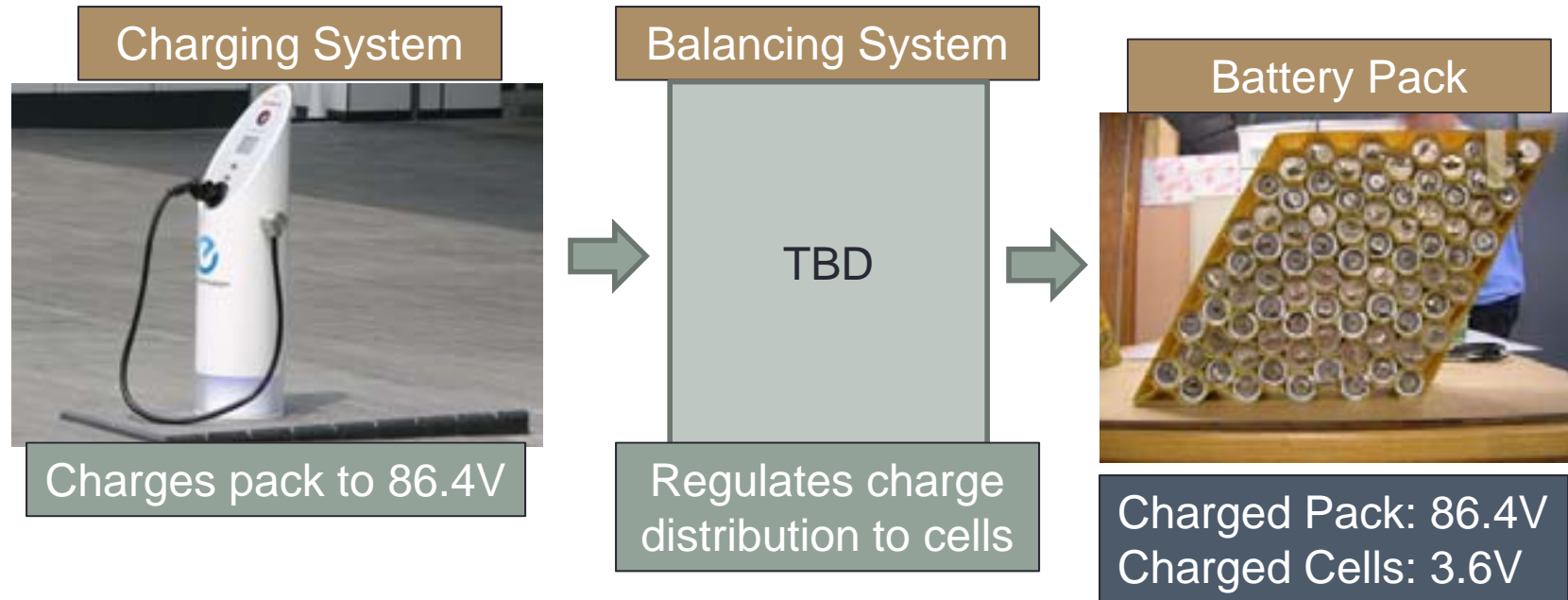
- Produces 12V and 5V from pack range: 60-86.4V and can deliver high current.
- Implemented Linear Technology LT3810 chip.
- Unresolved problems led us to seek commercial options.

Battery Balancing

- Circuitry needed to keep cell string voltages between 2.5V-3.6V while charging the pack to 86.4V



Battery Balancing Structure



Battery Balancing

- Circuitry needed to keep cell string voltages between 2.5V-3.6V during charging.
- Texas Instruments Battery Balancing Chip selected
- Support circuitry designed.
- One chip per module
- Programming Functionality

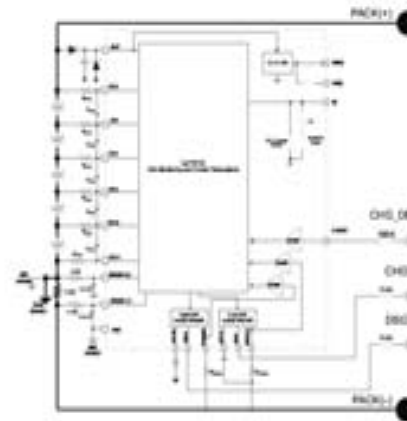
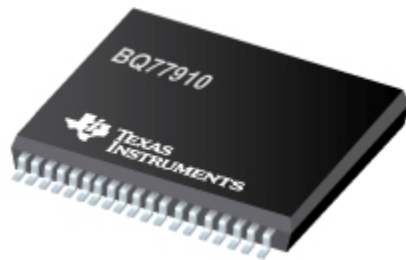
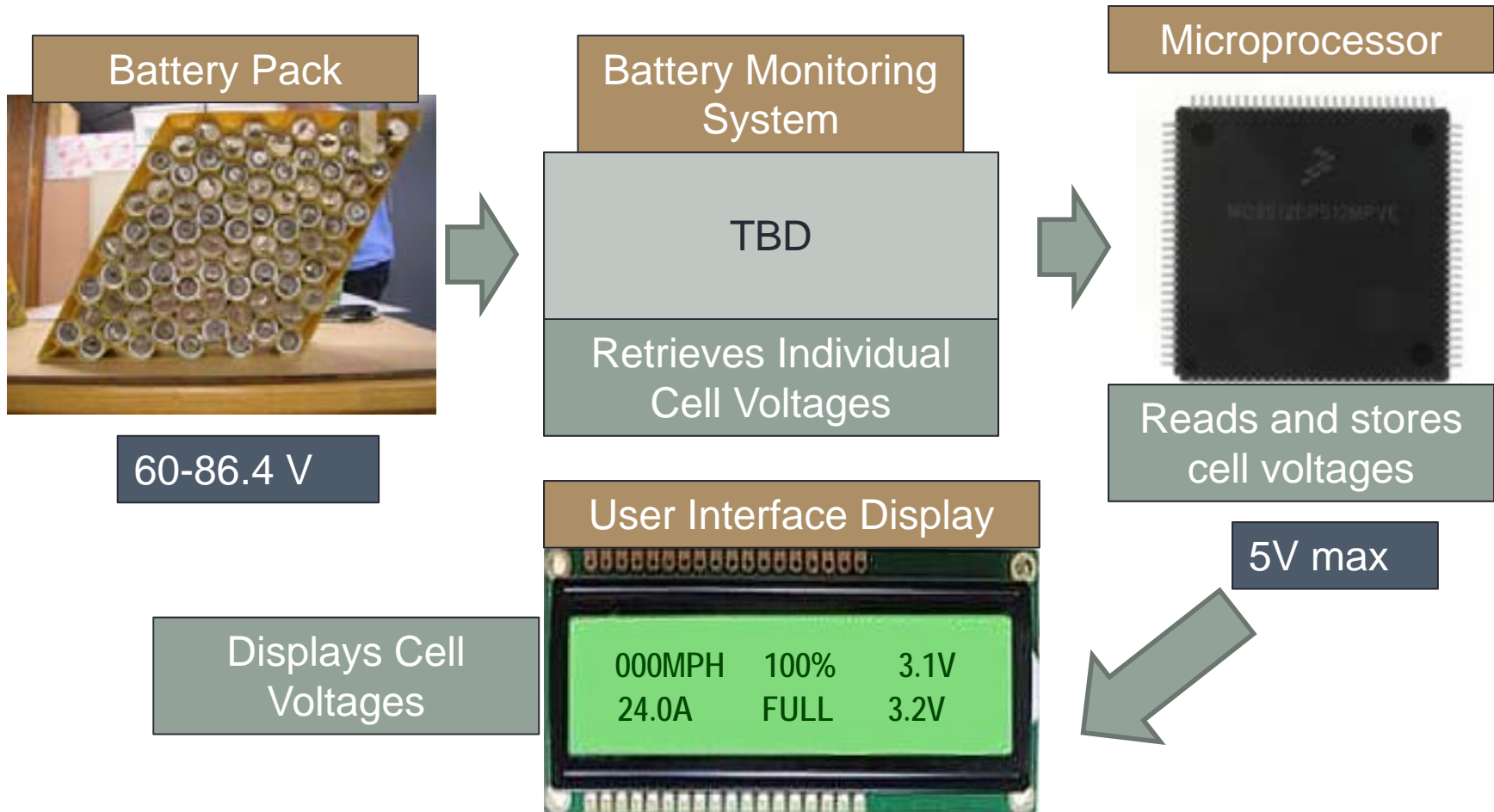
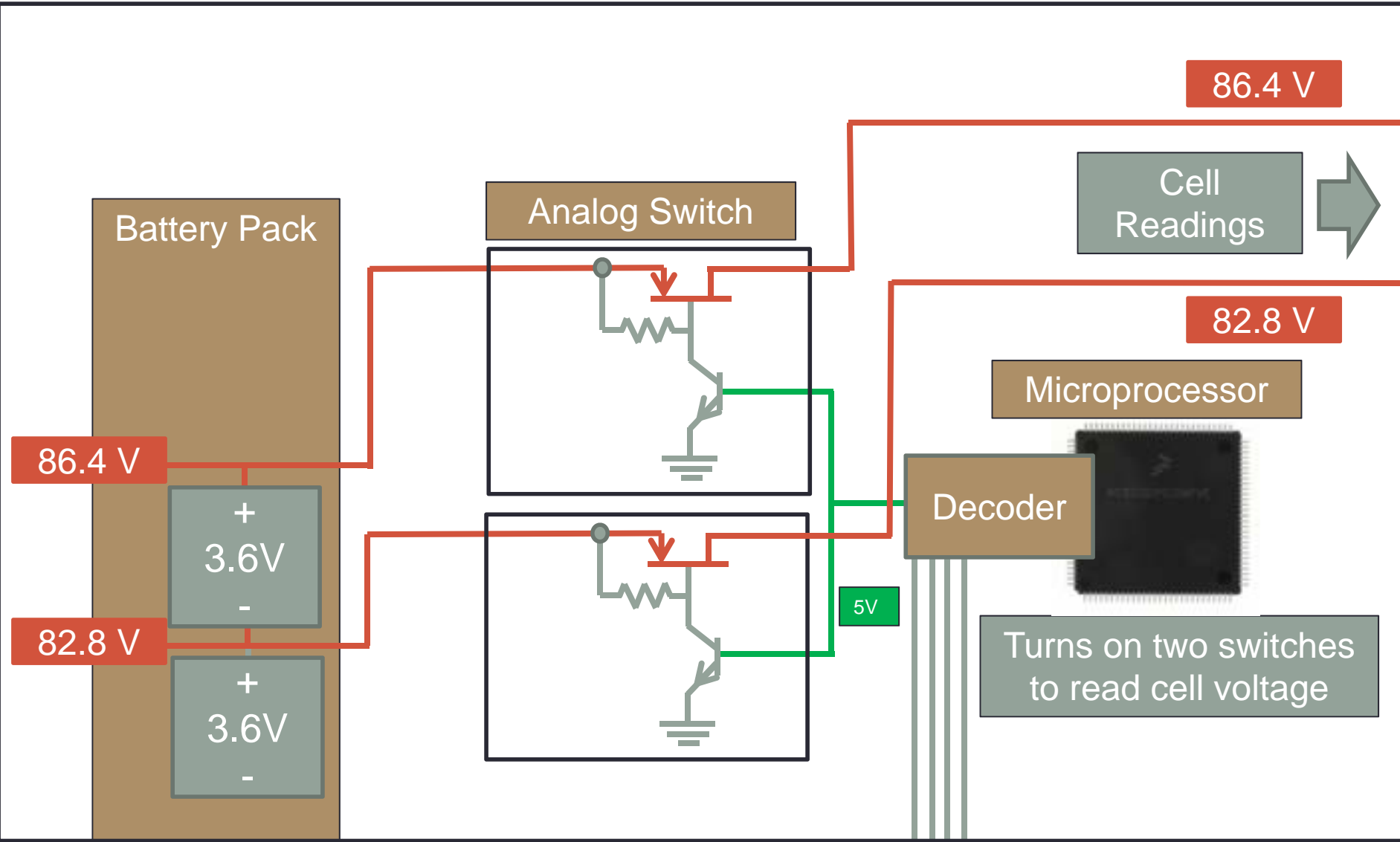


Figure 10. Single Power Path, No FETs

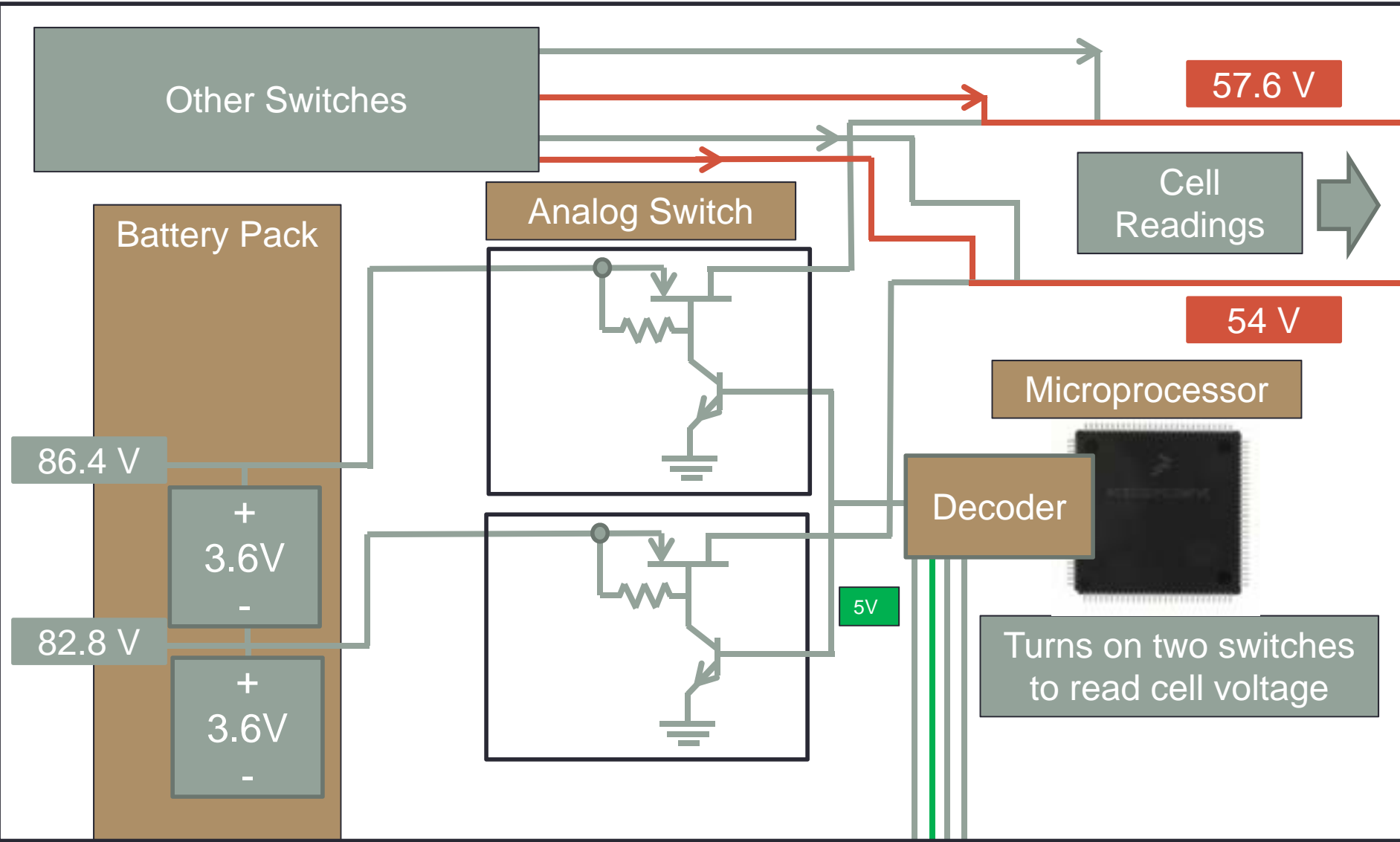
Battery Monitoring Structure



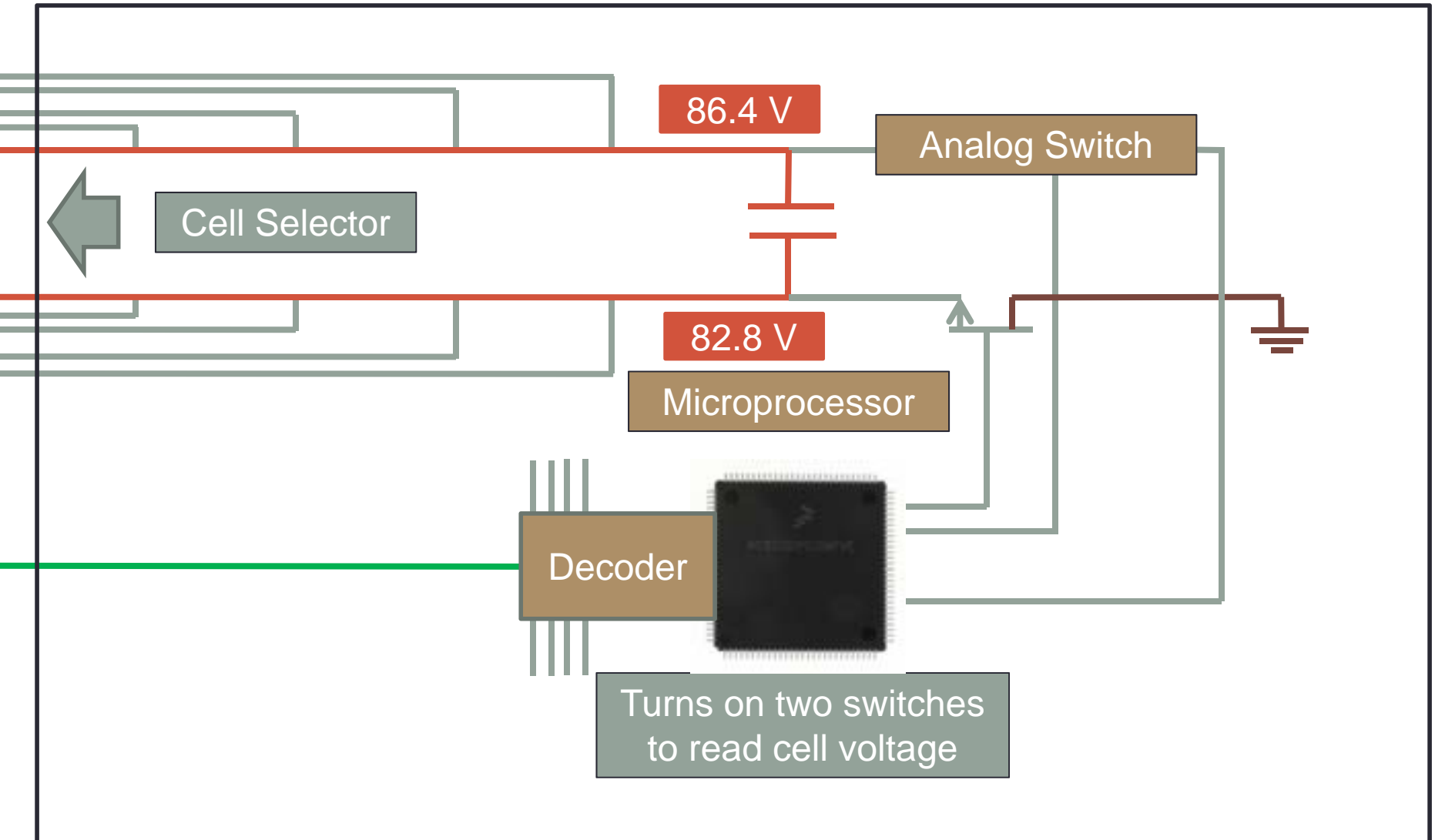
Battery Balancing Cell Selection



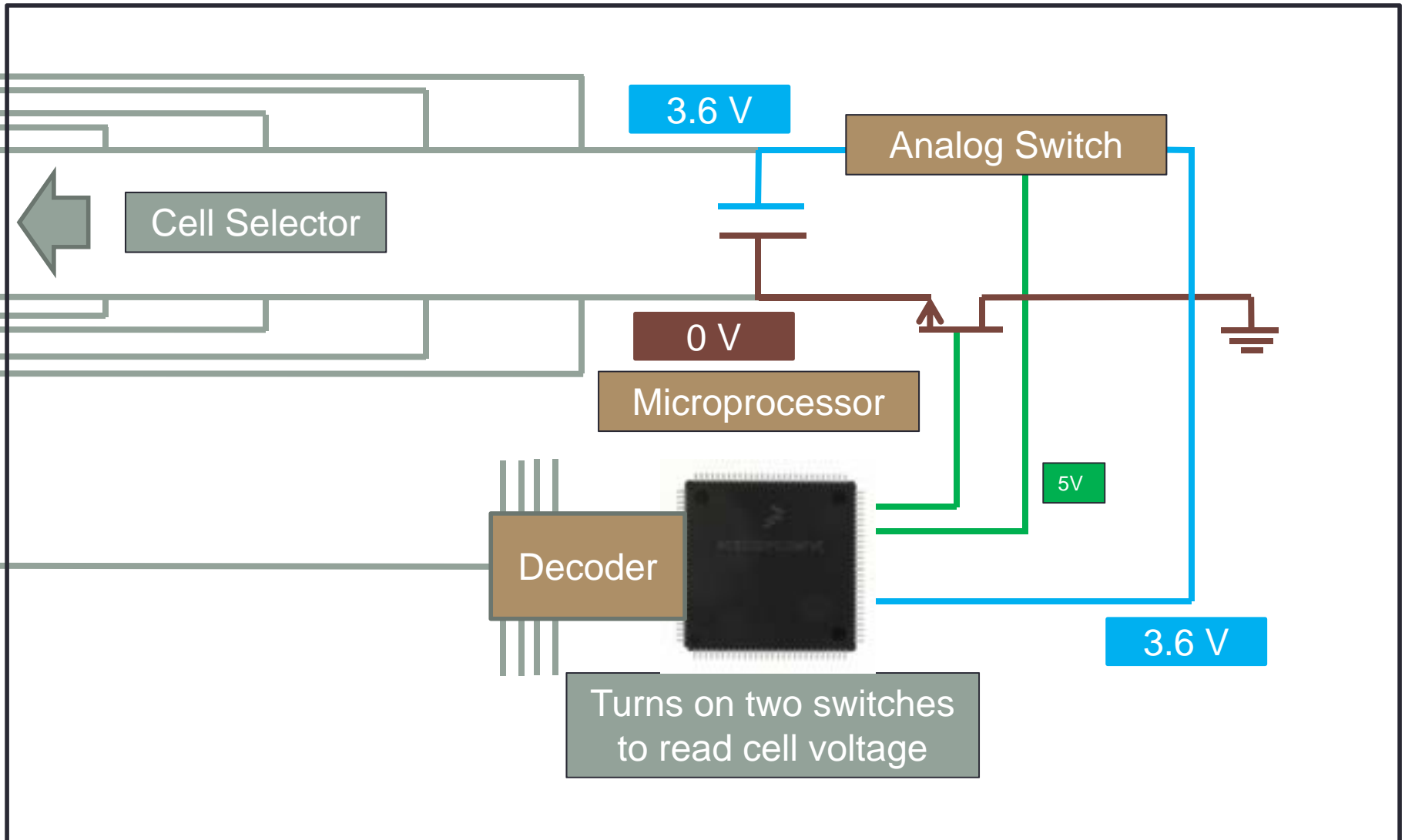
Battery Balancing Cell Selection



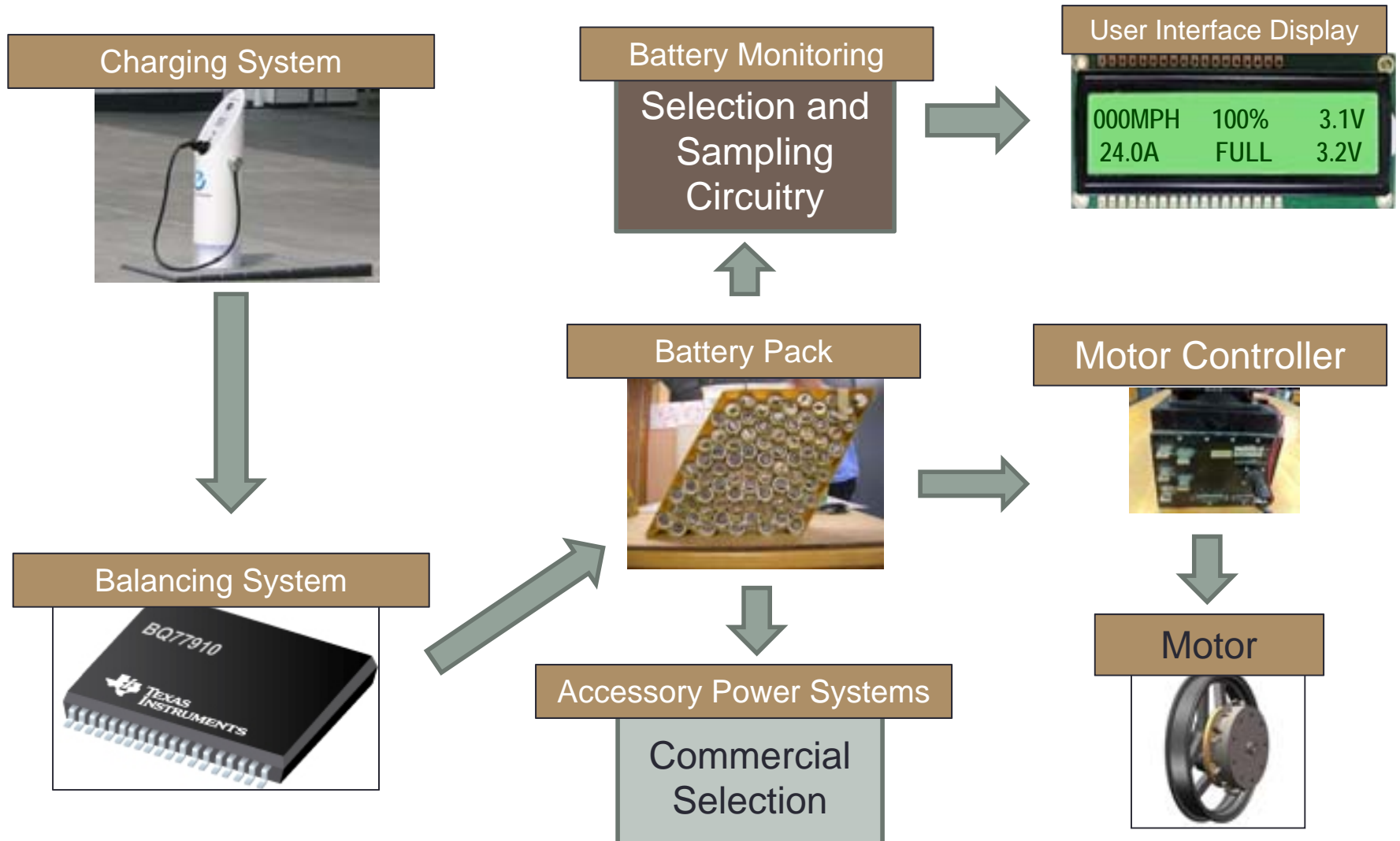
Battery Balancing Cell Readings



Battery Balancing Cell Readings



Electrical Systems Structure



Thanks

- Dr. Pratt
- Paul Myers
- Predecessors:
 - Sara Finn
 - Eric Hornberger
 - Jon Wolgemuth